AMENDMENTS TO THE SPECIFICATION:

Please amend the abstract as follows:

A positioning apparatus according to the present invention includes having a brushless

motor, a positioning mechanism to position a movable member within a predetermined movable

range in accordance with rotation of the brushless motor, and a motor control circuit to rotate a

rotor of the brushless motor by sequentially supplying a driving pulse to a plurality of fixed coils

of the brushless motor. The motor control circuit includes[[,]] a driving pulse generator to

generate the driving pulse, a present stage number detector to detect a present stage number of

the rotor in accordance with an output signal from [[a]] at least one magneto-sensitive device of

the brushless motor, an initializer to move the movable member to at least a forward traveling

limit or a backward traveling limit within the movable range so as to set the rotor present stage

number as a forward traveling limit stage number or a backward traveling stage number when the

movable member reaches the forward traveling limit or the backward traveling limit, and a speed

reducer to reduce a rotating speed of the brushless motor by reducing power of the driving pulse

when the rotor present stage number is equal to at least [[the]] a forward traveling limit stage

number or the a backward traveling stage number.

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